

Mark Scheme (Results)

Summer 2008

GCE

GCE Mathematics (6676/01)

6676 Further Pure FP3 Mark Scheme

Question Number	Scheme	Marks
1.	$\left(\frac{dy}{dx}\right)_0 = 0 + \cos 0.6 \quad (= 0.825335\dots)$ $y_1 \approx 0.05 \left(\frac{dy}{dx}\right)_0 + y_0 \quad (= 0.05 \times 0.825335\dots + 0.6)$ $y_1 \approx 0.641266\dots$ $= 0.6413 \text{ (4 d.p.)}$ $\left(\frac{dy}{dx}\right)_1 = 0.05 + \cos 0.641266\dots \quad [\text{or } 0.05 + \cos(0.6 + 0.05 \cos 0.6)]$ $= 0.851338\dots$ $y_2 \approx 0.05 \left(\frac{dy}{dx}\right)_1 + y_1 \quad (= 0.05 \times 0.851338\dots + 0.641266\dots)$ <p style="text-align: center;">Requires use of the differential equation to find $\left(\frac{dy}{dx}\right)_1$</p> $y_2 \approx 0.683833\dots$ $= 0.6838 \text{ (4 d.p.)}$	May be implicit B1 M1 Allow awrt A1 A1ft M1 A1 (6)

Degree mode in calculator:

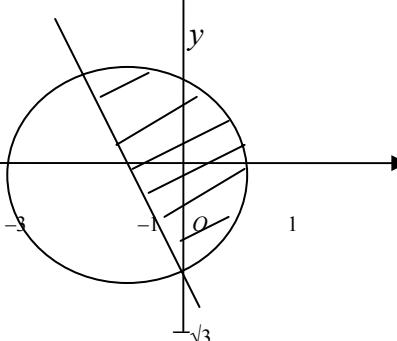
Gives answers: 0.6500 (0.64999...)

0.7025 (0.70248...)

This can score B1 M1 A0 A1ft M1 A0

Question Number	Scheme	Marks
2. (a)	$\begin{pmatrix} 1 & p & 2 \\ 0 & 3 & q \\ 2 & p & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = \lambda \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$ $\begin{pmatrix} 1+2p+2 \\ 6+q \\ 2+2p+1 \end{pmatrix} = \begin{pmatrix} \lambda \\ 2\lambda \\ \lambda \end{pmatrix}$ is M1 A1 (2 eqns implied) $\begin{pmatrix} 3+2p \\ 6+q \\ 3+2p \end{pmatrix} \Rightarrow 6+q = 2(3+2p)$ is M1 A1 (2 eqns, use of parameter implied) $1+2p+2=\lambda \quad 6+q=2\lambda \quad \text{M: Two equations, one in } p, \text{ one in } q$ $\therefore 6+q=6+4p \Rightarrow q=4p \quad (*)$	
		M1 A1 A1 (3)
	$\begin{vmatrix} -4 & p & 2 \\ 0 & -2 & 4p \\ 2 & p & -4 \end{vmatrix} = 0 \quad \text{or} \quad \begin{vmatrix} 1-\lambda & p & 2 \\ 0 & 3-\lambda & 4p \\ 2 & p & 1-\lambda \end{vmatrix} = 0$ (or with q instead of $4p$) $[-4(8-4p^2) - p(0-8p) + 2(0+4)] = 0 \quad p^2 = 1 \quad \text{or} \quad pq = 4$ $p < 0 \quad p = -1 \quad q = -4 \quad \text{M: Use } q = 4p \text{ to find value of } p \text{ and of } q$ A1: Positive values must be rejected	M1 A1 dM1 A1 (4)
(b)	$-4x-y+2z=0, -2y-4z=0, 2x-y-4z=0 \quad \text{Any 2 eqns, with value of } p$ $2x=-y=2z \quad (\text{or 2 separate equations})$ E.vector is $k \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} \quad (\text{Any non-zero value of } k)$	M1 M1 A1 (3)
		(10)
	(a) Assuming a value for λ , e.g. $\lambda=1$, gives M1 A0 A0. (a) Assuming result and working ‘backwards’: $\begin{pmatrix} 1 & p & 2 \\ 0 & 3 & 4p \\ 2 & p & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 3+2p \\ 6+4p \\ 3+2p \end{pmatrix} = \begin{pmatrix} 3+2p \\ 3+2p \\ 3+2p \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}, \quad \text{gives M1 A0 A0}$ (b) Alternative: $\begin{pmatrix} 1 & p & 2 \\ 0 & 3 & 4p \\ 2 & p & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 5 \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad \text{or} \quad \begin{pmatrix} -4 & p & 2 \\ 0 & -2 & 4p \\ 2 & p & -4 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad (\text{or } q \text{ instead of } 4p)$ $x+py+2z=5x, 3y+4pz=5y, 2x+py+z=5z$ $py+2z=4x \text{ (i)}, 2pz=y \text{ (ii)}, 2x+py=4z \text{ (iii)}$ From (i) and (iii) $py=2z$ From (ii) $p^2=1 \quad (\text{or equiv. in terms of } p \text{ and/or } q)$ $p < 0, p = -1, q = -4 \quad \text{A1: Positive values must be rejected}$	M1 A1 dM1 A1
	(b) Using the eigenvector $\begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$ scores <u>no marks</u> in this part.	

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3. (a)	$(x^2 + 1) \frac{d^3 y}{dx^3} + 2x \frac{d^2 y}{dx^2} = 4y \frac{dy}{dx} + (1 - 2x) \frac{d^2 y}{dx^2} - 2 \frac{dy}{dx}$ $(x^2 + 1) \frac{d^3 y}{dx^3} = (1 - 4x) \frac{d^2 y}{dx^2} + (4y - 2) \frac{dy}{dx} \quad (*)$	M1 A1 A1 (3)
(b)	$\left(\frac{d^2 y}{dx^2} \right)_0 = 3$ $\left(\frac{d^3 y}{dx^3} \right)_0 = 5$ Follow through: $\frac{d^3 y}{dx^3} = \frac{d^2 y}{dx^2} + 2$ $y = 1 + x + \frac{3}{2}x^2 + \frac{5}{6}x^3 \dots$	B1 B1ft M1 A1 (4)
(c)	$x = -0.5, \quad y \approx 1 - 0.5 + 0.375 - 0.104166\dots$ $= 0.77 \text{ (2 d.p.)}$	[awrt 0.77] B1 (1) (8)
	(a) M: Use of product rule (at least once) and implicit differentiation (at least once). (b) M: Use of series expansion with values for the derivatives (can be allowed without the first term 1, and can also be allowed if final term uses 3 rather than 3!)	

4.	<p>(a) $z - 3 + z = 2 x + iy \Rightarrow (x - 3)^2 + y^2 = 4x^2 + 4y^2$ $\therefore x^2 + y^2 + 2x - 3 = 0$ $(x + 1)^2 + y^2 = 4$ Centre $(-1, 0)$, radius 2</p>	M1 A1 M1 A1, A1 (5)
(b)	 <p>Circle, centre on x-axis B1 $C(-1, 0), r = 2$ dB1ft Follow through centre and radius, but dependent on first B1. There must be indication of their '-3', '-1' or '1' on the x-axis and no contradictory evidence for their radius.</p> <p>Straight line B1 Straight line through $(-1, 0)$, or perp. bisector of $(-3, 0)$ and $(0, \sqrt{3})$. B1 Straight line through point of int. of circle & -ve y-axis, or through $(0, -\sqrt{3})$ B1</p>	B1 dB1 B1 B1 B1 (5)
(c)	<p>Shading (only) inside circle Inside correct circle and all of the correct side of the correct line... this mark is dependent on <u>all</u> the previous B marks in parts (b) and (c).</p>	B1 dB1 (2) (12)
	<p>(a) 1st M: Use $z = x + iy$, and attempt square of modulus of each side. Not squaring the 2 on the RHS would be M1 A0.</p> <p>2nd M: Attempting to express in the form $(x - a)^2 + (y - b)^2 = k$, or attempting centre and radius from the form $x^2 + y^2 + 2gx + 2fy + c = 0$</p>	

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5. (a)	$\begin{pmatrix} k & -2 \\ 1-k & k \end{pmatrix} \begin{pmatrix} t \\ 2t \end{pmatrix} = \begin{pmatrix} t(k-4) \\ t(1+k) \end{pmatrix}$ $t(1+k) = 2t(k-4)$ $k = 9$	M1 dM1 A1 (3)
(b)	$\det \mathbf{A} = k^2 + 2(1-k) = (k-1)^2 + 1, \text{ which is always positive}$ $\mathbf{A} \text{ is non-singular}$	M1 M1 A1cs (3)
(c)	$\mathbf{A}^{-1} = \frac{1}{k^2 - 2k + 2} \begin{pmatrix} k & 2 \\ k-1 & k \end{pmatrix}$	M1 A1 (2)
(d)	$k = 3, \quad \mathbf{A}^{-1} = \frac{1}{5} \begin{pmatrix} 3 & 2 \\ 2 & 3 \end{pmatrix}$ $\mathbf{Ap} = \mathbf{q} \Rightarrow \mathbf{p} = \mathbf{A}^{-1}\mathbf{q} \quad \mathbf{p} = \frac{1}{5} \begin{pmatrix} 3 & 2 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} 4 \\ -3 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 6 \\ -1 \end{pmatrix}$ $\text{Alt. } \begin{pmatrix} 3 & -2 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 4 \\ -3 \end{pmatrix} \Rightarrow 3x - 2y = 4, -2x + 3y = -3 \quad \text{B1}$ <p>M1 A1 for solving two sim. eqns. in x and y to give $x = 1.2, y = -0.2$ (o.e.)</p>	B1 M1 A1 (3) (11)
	(b) 2 nd M: Alternative is to use quadratic formula on the quadratic equation, or to use the discriminant, with a <u>comment</u> about ‘no real roots’, or ‘can’t equal zero’, or a comment about the condition for singularity. $\left(x = \frac{2 \pm \sqrt{4-8}}{2} \right)$ <p>A1 Conclusion.</p> (c) M: Need $\frac{1}{\det \mathbf{A}}$, k 's unchanged and attempt to change sign for either -2 (leaving as top right) or $1-k$ (leaving as bottom left). (d) M: Requires an attempt to multiply the matrices.	

Question Number	Scheme	Marks
6. (a)	$(\cos \theta + i \sin \theta)^1 = \cos \theta + i \sin \theta \quad \therefore \text{true for } n = 1$ Assume true for $n = k$, $(\cos \theta + i \sin \theta)^k = \cos k\theta + i \sin k\theta$ $(\cos \theta + i \sin \theta)^{k+1} = (\cos k\theta + i \sin k\theta)(\cos \theta + i \sin \theta)$ $= \cos k\theta \cos \theta - \sin k\theta \sin \theta + i(\sin k\theta \cos \theta + \cos k\theta \sin \theta)$ (Can be achieved either from the line above or the line below) $= \cos(k+1)\theta + i \sin(k+1)\theta$ Requires full justification of $(\cos \theta + i \sin \theta)^{k+1} = \cos(k+1)\theta + i \sin(k+1)\theta$ $(\therefore \text{true for } n = k+1 \text{ if true for } n = k) \quad \therefore \text{true for } n \in \mathbb{Z}^+$ by induction	B1 M1 M1 A1 A1cso (5)
(b)	$\cos 5\theta = \operatorname{Re}[(\cos \theta + i \sin \theta)^5]$ $= \cos^5 \theta + 10 \cos^3 \theta i^2 \sin^2 \theta + 5 \cos \theta i^4 \sin^4 \theta$ $= \cos^5 \theta - 10 \cos^3 \theta \sin^2 \theta + 5 \cos \theta \sin^4 \theta$ $= \cos^5 \theta - 10 \cos^3 \theta (1 - \cos^2 \theta) + 5 \cos \theta (1 - \cos^2 \theta)^2$ $\cos 5\theta = 16 \cos^5 \theta - 20 \cos^3 \theta + 5 \cos \theta$ (*)	M1 A1 M1 M1 A1cso (5)
(c)	$\frac{\cos 5\theta}{\cos \theta} = 0 \Rightarrow \cos 5\theta = 0$ $5\theta = \frac{\pi}{2} \quad \theta = \frac{\pi}{10}$ $x = 2 \cos \theta, \quad x = 2 \cos \frac{\pi}{10}$ is a root (*)	M1 A1 A1 (3) (13)
	(a) <u>Alternative:</u> For the 2 nd M mark: $(e^{ik\theta})(e^{i\theta}) = e^{i\theta(k+1)}$ (b) <u>Alternative:</u> $\left(z + \frac{1}{z}\right)^5 = z^5 + 5z^4\left(\frac{1}{z}\right) + 10z^3\left(\frac{1}{z}\right)^2 + 10z^2\left(\frac{1}{z}\right)^3 + 5z\left(\frac{1}{z}\right)^4 + \left(\frac{1}{z}\right)^5$ M1 $= 2 \cos 5\theta + 10 \cos 3\theta + 20 \cos \theta$ A1 $(2 \cos \theta)^5 = \dots \text{ and attempt to put } \cos 3\theta \text{ in powers of } \cos \theta$ M1 Correct method (or formula) for putting $\cos 3\theta$ in powers of $\cos \theta$ M1 $\cos 5\theta = 16 \cos^5 \theta - 20 \cos^3 \theta + 5 \cos \theta$ A1cso (c) <u>Alternatives:</u> (i) Substitute given root into $x^4 - 5x^2 + 5$: $\left(2 \cos \frac{\pi}{10}\right)^4 - 5\left(2 \cos \frac{\pi}{10}\right)^2 + 5 = 2^4 \left(\cos \frac{\pi}{10}\right)^4 - 5 \times 2^2 \left(\cos \frac{\pi}{10}\right)^2 + 5$ M1 ‘Multiply by $\cos \theta$ ’ and use result from part (b): ... = $\cos \frac{5\pi}{10}$ A1 $= 0$ and conclusion A1 (ii) Use $5\theta = \frac{\pi}{2}$ in result from part (b) M1 $16\left(\cos \frac{\pi}{10}\right)^5 - 20\left(\cos \frac{\pi}{10}\right)^3 + 5\left(\cos \frac{\pi}{10}\right)$ and divide by $\cos \theta$ A1 $= 0$ and conclusion A1	

Question Number	Scheme	Marks
7. (a)	$\vec{PQ} = \mathbf{i} - \mathbf{j} + 2\mathbf{k}$, $\vec{PR} = 2\mathbf{i} - 3\mathbf{j} + 3\mathbf{k}$ $\vec{PQ} \times \vec{PR} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & -1 & 2 \\ 2 & -3 & 3 \end{vmatrix} = 3\mathbf{i} + \mathbf{j} - \mathbf{k}$	B1 M1 A1 (3)
(b)	$\mathbf{r} \cdot (3\mathbf{i} + \mathbf{j} - \mathbf{k}) = (\mathbf{i} - \mathbf{k}) \cdot (3\mathbf{i} + \mathbf{j} - \mathbf{k})$ [may use \vec{OQ} or \vec{OR}] $\mathbf{r} \cdot (3\mathbf{i} + \mathbf{j} - \mathbf{k}) = 4$ o.e. ft from (a)	M1 A1ft (2)
(c)	$3x + y - z = 4$ (i), $x - 2y - 5z = 6$ (ii) (i) $\times 2 +$ (ii) $7x - 7z = 14$, $x = z + 2$ (M: Eliminate one variable) In (ii) $z + 2 - 2y - 5z = 6$, $y + 2 = -2z$ (M: Substitute back) $\therefore x = z + 2$ and $y + 2 = -2z$ o.e. ($y = 2 - 2x$) (Two correct ‘3-term’ equations) $\frac{x-2}{(1)} = \frac{y+2}{-2} = \frac{z}{(1)}$ o.e. (M: Form cartesian equations)	M1 M1 A1 M1 A1 (5)
(d)	Writing down direction vector of \vec{PS} from part (c).	M1
(e)	$\vec{QR} = \mathbf{i} - 2\mathbf{j} + \mathbf{k} = \vec{PS}$ $\therefore PS \parallel QR$ (or cross-product = 0) $\vec{PT} = 4\mathbf{i} + 2\mathbf{j}$ (or $\vec{QT} = 3\mathbf{i} + 3\mathbf{j} - 2\mathbf{k}$ or $\vec{RT} = 2\mathbf{i} + 5\mathbf{j} - 3\mathbf{k}$) Volume = $\frac{1}{3} \vec{PQ} \times \vec{PR} \cdot \vec{PT} = \frac{1}{3} (3\mathbf{i} + \mathbf{j} - \mathbf{k}) \cdot (4\mathbf{i} + 2\mathbf{j}) $ ft from (a) (Instead of $\vec{PQ} \times \vec{PR}$, it could be $\vec{PQ} \times \vec{QR}$ or $\vec{PR} \times \vec{QR}$) $= \frac{1}{3} (12 + 2)$ $= 4\frac{2}{3}$ o.e.	M1 A1ft A1 (3) (15)
	(a) If both vectors are ‘reversed’, B0 M1 A1 is possible (c) <u>Alternative:</u> Direction of line: $\begin{pmatrix} 1 \\ -2 \\ -5 \end{pmatrix} \times \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} = 7 \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$ M2 A1 Through $P(1, 0, -1)$: $\frac{x-1}{1} = \frac{y}{-2} = \frac{z+1}{1}$ M1 A1 (e) <u>Alternative:</u> $\frac{1}{3} \begin{vmatrix} 4 & 2 & 0 \\ 1 & -1 & 2 \\ 2 & -3 & 3 \end{vmatrix}$ gives M1 A1 directly. Here ft from 1 st line of part (a). <u>Special case:</u> $\frac{1}{6}$ or $\frac{1}{2}$ instead of $\frac{1}{3}$, but method otherwise correct: M1 A0 A0	